

Inputs	Component/PID Only	Measured/PID Values				Units Measured/PID
		KOEO	Hot Idle	48 KM/H (30 MPH)	89 KM/H (55 MPH)	
MAP	MAP Sensor	100 (14.50)	36 (5.22)	55 (7.98)	27 (3.92)	kPa (PSI)
MAP_V	MAP Sensor	1.62	0.63	0.92	0.56	VOLTS
MIL_DIS	PID	0	0	0	0	KM (MILES)
MISFIRE	PID	FALSE	FALSE	FALSE	FALSE	TRUE/FALSE
MP_LRN	PID	TRUE	TRUE	TRUE	TRUE	TRUE/FALSE
NUM_MISFIRE	PID	0	0	0	0	COUNT
O2S11_CUR	HO2S11 Sensor	(I)	switching	switching	switching	mA/uA
O2S11_IMP	HO2S11 Sensor	4.93	1.01	1.02	1.02	VOLTS
O2S11_READY	HO2S11 Sensor	NO	YES	YES	YES	YES/NO
O2S11_TR	HO2S11 Sensor	0	0	0	0	Kohm
O2S12	HO2S12 Sensor	1.61 (I)	1.61 (D)	0.74 (D)	0.77 (D)	VOLTS
OCTADJ_R_LRND	PID	0	0	0	0	%
OSS_SRC	OSS Sensor	0	0	1330	2529	RPM
RO2FT1	PID	0	-0.02	0.02	-0.01	%
RPM	CKP Sensor	0	951	2472	1854	RPM
SHRTFT1	PID	(I)	-10 TO +10	-10 TO +10	-10 TO +10	%
SYNC	PID	NO	YES	YES	YES	YES/NO
TCBP	TCBP Sensor	100.1 (14.52)	100.4 (14.56)	105.3 (15.27)	138.4 (20.07)	kPa (PSI)
TCBP_V	TCBP Sensor	1.62	1.62	1.69	2.20	VOLTS
TP1_LRN_TRIM	ETBTPS	15.13	15.13	15.13	15.13	DEG
TP1_PER	ETBTPS	23	15	21	23	%
TP1_V	ETBTPS	3.84	4.22	3.93	3.86	VOLTS
TP2_LRN_TRIM	ETBTPS	15.13	15.13	15.13	15.13	DEG
TP2_PER	ETBTPS	23	15	21	23	%
TP2_V	ETBTPS	1.16	0.78	1.07	1.14	VOLTS
TP_MAXDIFF	PID	-0.06	0	0	-0.06	%
TP_REL	PID	11	4	8	23	VOLTS
TQ_CNTRL	PID	ANTI THEFT	IDLE SPEED CONTROL	NONE REQUESTED	CRUISE CONTROL	STATUS
TURBO_BP1_STAT	TCBY Valve	NO FAULT	NO FAULT	NO FAULT	NO FAULT	FAULT/ NO FAULT
VCTSYS	PID	DISABLED	ENABLED	CLOSED LOOP	CLOSED LOOP	ENABLED/ DISABLED